

# How to Win SV-COMP with Symbolic Execution

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KLEE Workshop 2022

## **SV-COMP** = Competition on Software Verification

- organized by Dirk Beyer since 2012
- task = to decide whether a given C (or Java) program satisfies a given property (and produce a witness)
- considered properties
  - reachability safety
  - memory safety
  - no overflows
  - termination
- resources: 8 cores, 900 s of CPU time, 15 GB of memory

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## **SV-COMP 2022**

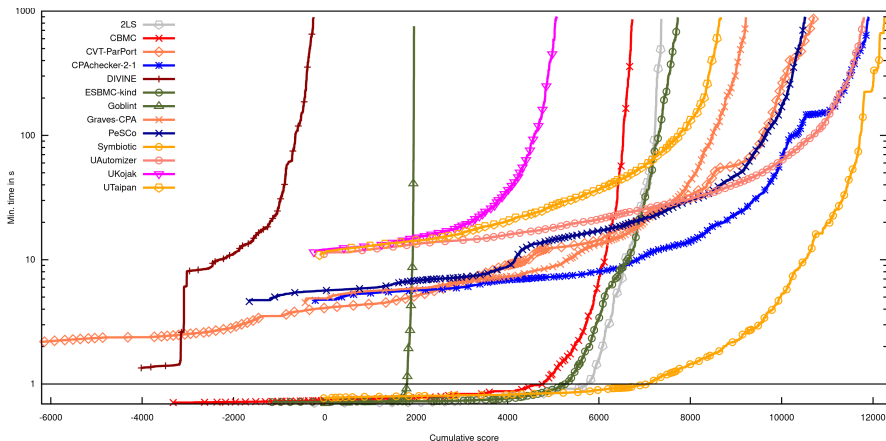
- 15 648 verification tasks
- 40 verification tools (including 12 hours concours)
- 12 of them use symbolic execution

# SYMBIOTIC at SV-COMP

- participating since 2013 (every year except 2015)
- 4 gold medals in **MemSafety** (2018, 2019, 2021, 2022)
- 3 gold medals in **SoftwareSystems** (2020, 2021, 2022)
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# why SYMBIOTIC uses symbolic execution



Jiří Slabý



Marek Trtík

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## pros

- + no false alarms
- + KLEE is available
- + KLEE easily finds bugs

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- struggles with program loops
- rarely finishes on real programs
- KLEE skips some runs



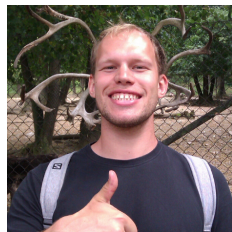
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Marek Chalupa

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## 1 how SYMBIOTIC works

- Chalupa and Strejček: *Symbiotic: Slice and Verify*. Under review.
- Chalupa, Mihalkovič, Řečtáčková, Zaoral, and Strejček: *Symbiotic 9: String Analysis and Backward Symbolic Execution with Loop Folding*. TACAS 2022.

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- backward symbolic execution (BSE) =  $k$ -induction
- BSE + loop folding (BSELF)
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## JETKLEE

- our fork of KLEE optimized for verification
- analysis of all possible runs is more important than speed
- <https://github.com/staticafi/JetKlee>

|                            | KLEE | JETKLEE |
|----------------------------|------|---------|
| symbolic pointers          | ✓    | ✓       |
| symbolic-sized allocations | ✗    | ✓       |
| symbolic addresses         | ✗    | ✓       |

# JETKLEE and SLOWBEAST

## JETKLEE

- our fork of KLEE optimized for verification
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## SLOWBEAST

- symbolic executor implemented by Marek Chalupa in Python
- <https://gitlab.fi.muni.cz/xchalup4/slowbeast>

|                               | KLEE | JETKLEE | SLOWBEAST |
|-------------------------------|------|---------|-----------|
| symbolic pointers             | ✓    | ✓       | ✓         |
| symbolic-sized allocations    | ✗    | ✓       | ✓         |
| symbolic addresses            | ✗    | ✓       | ✓         |
| symbolic floats               | ✗    | ✗       | ✓         |
| parallel programs             | ✗    | ✗       | ✓         |
| backward symbolic exec. (BSE) | ✗    | ✗       | ✓         |
| BSE + loop folding (BSELF)    | ✗    | ✗       | ✓         |
| invariant generation          | ✗    | ✗       | ✓         |

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n = input();
i = 0;
while (i != n) {
    c = input();
    if (i == 0) {
        min = c;
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assert(min <= c);
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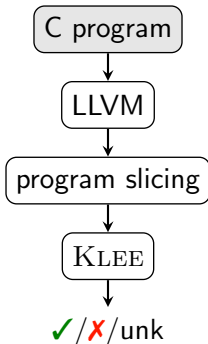


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# first workflow of SYMBIOTIC for reachability safety



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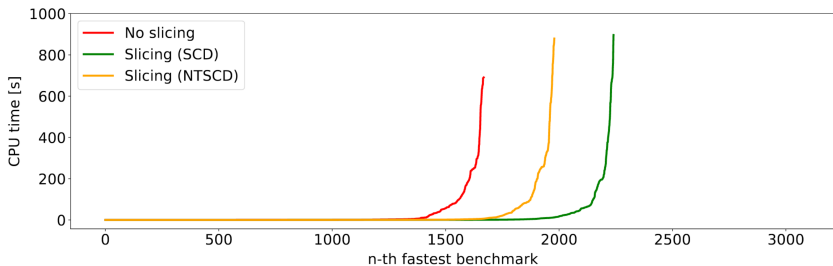
**standard control  
dependence (SCD)**

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**non-termination  
sensitive control  
dependence (NTSCD)**

# influence of slicing on performance of KLEE

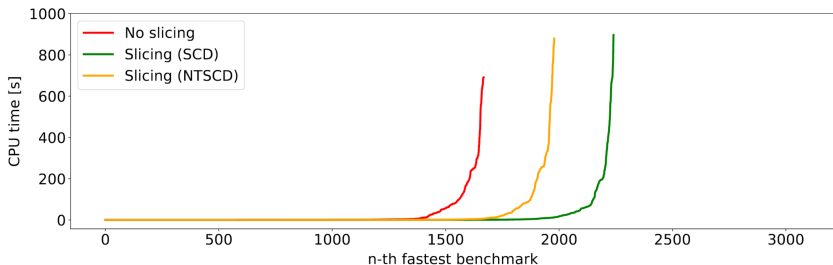
correct verification results produced by KLEE with slicing  
on reachability safety tasks of SV-COMP 2019





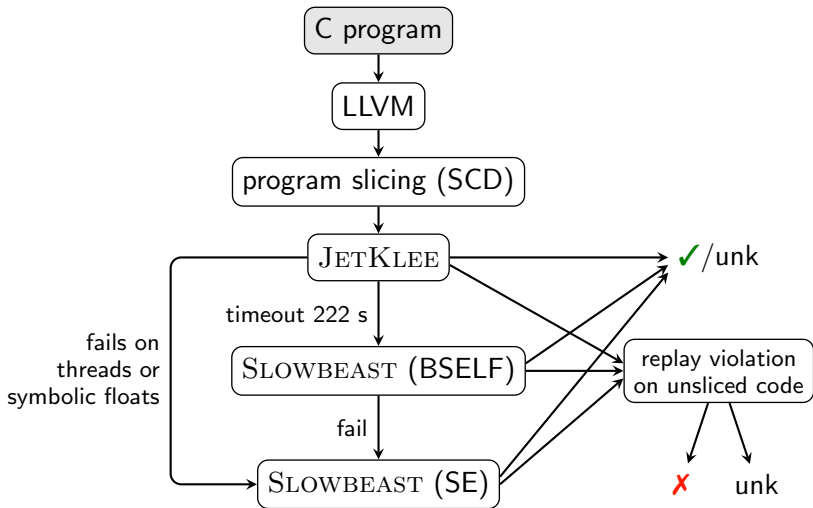
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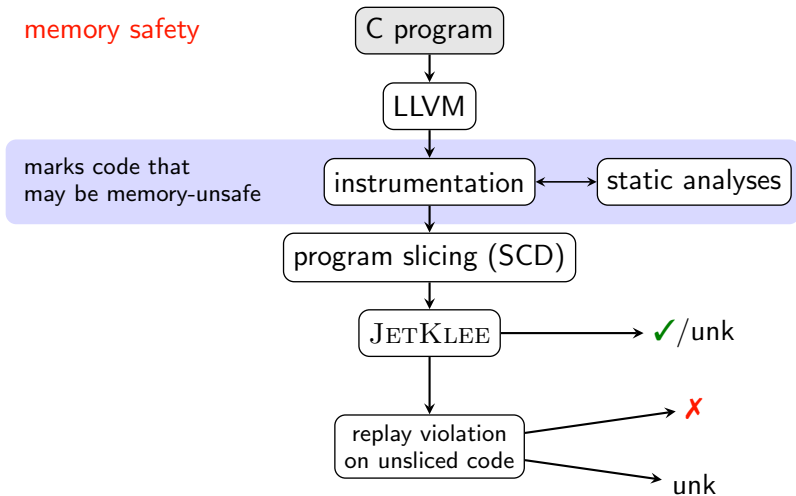
- slicing (SCD) also brought 43 incorrect verification results ✗
- Chalupa and Strejček: *Evaluation of Program Slicing in Software Verification*. iFM 2019.

# current workflow of SYMBIOTIC for reachability safety



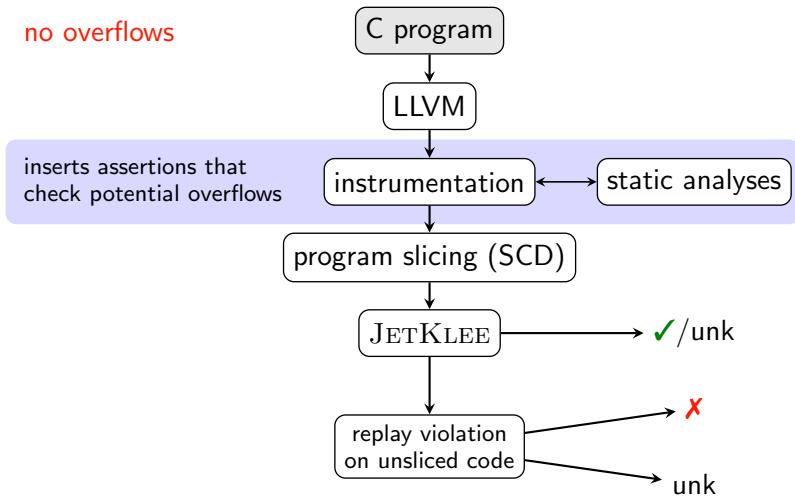
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memory safety



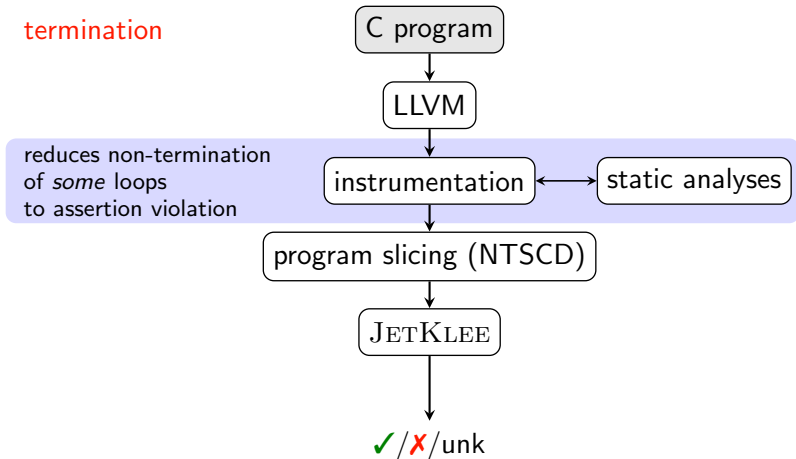
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no overflows

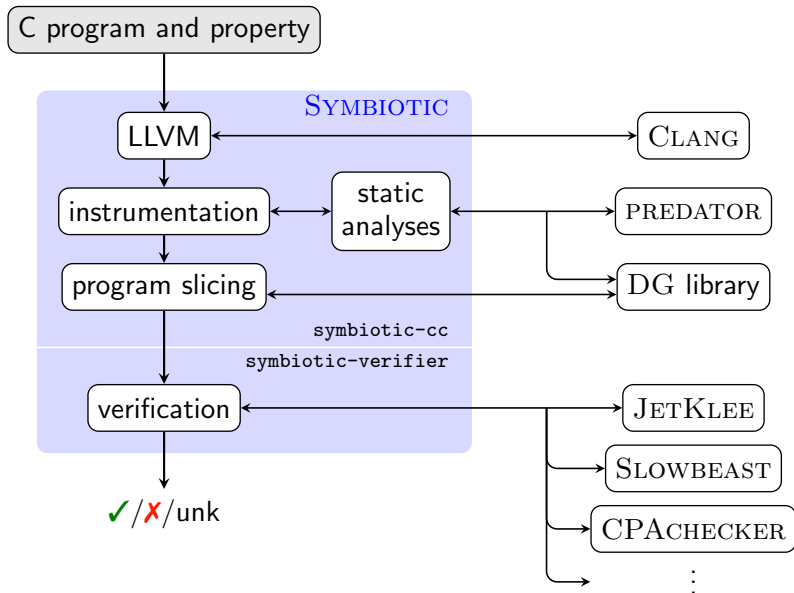


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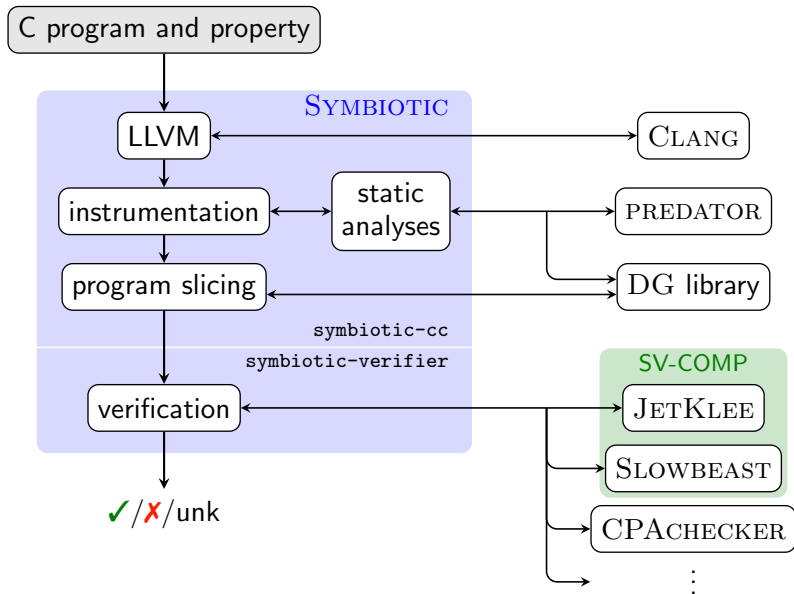
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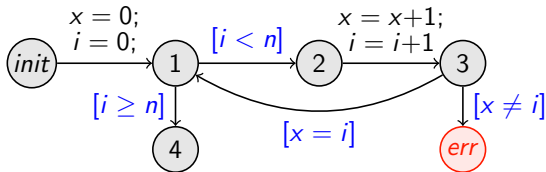
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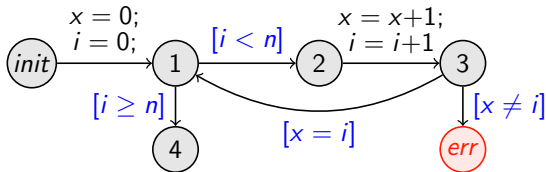
# control flow automata (CFA)

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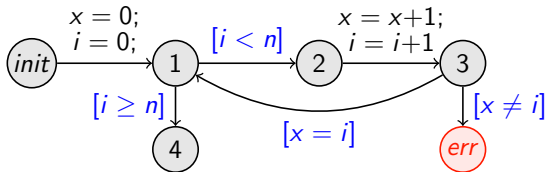
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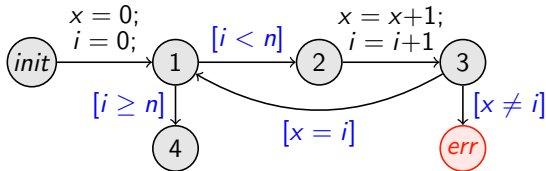
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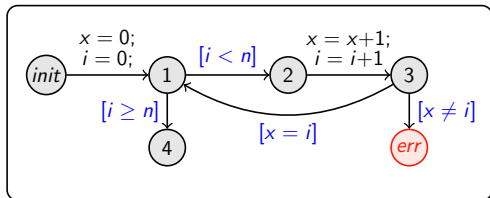
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- a path is **feasible** if it can be entirely executed
- a path is **unsafe** if it is feasible and ends in *err*, it is **safe** otherwise
- a CFA is **correct** if all paths starting in *init* are safe, it is **incorrect** otherwise

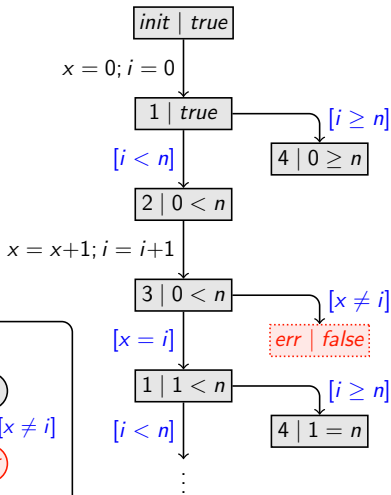
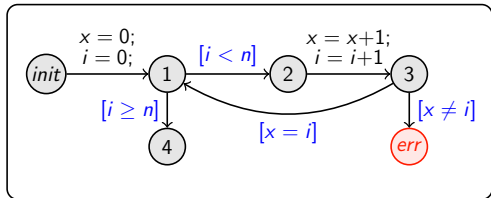
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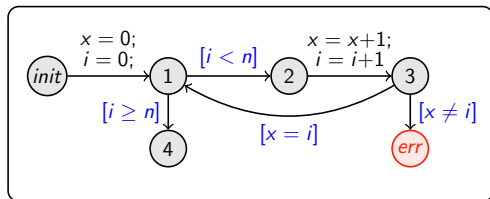
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# backward symbolic execution (BSE)

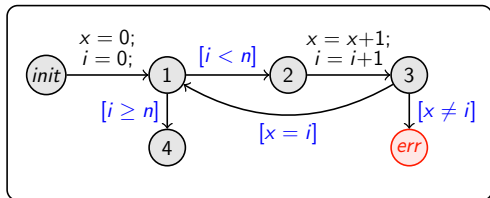
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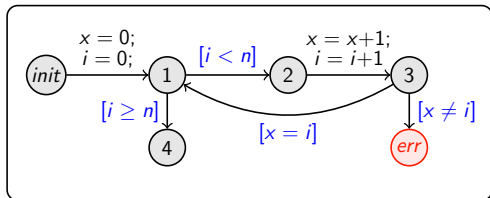
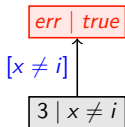
`err | true`





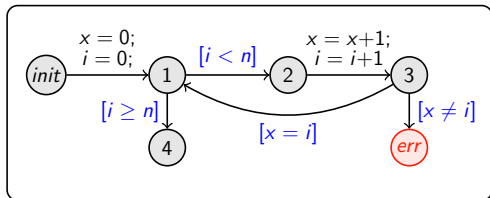
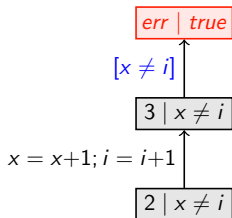
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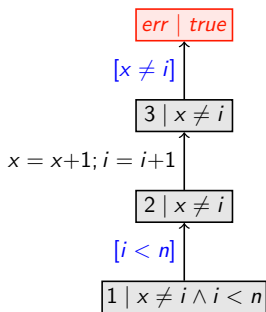
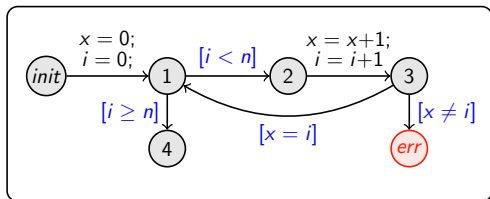
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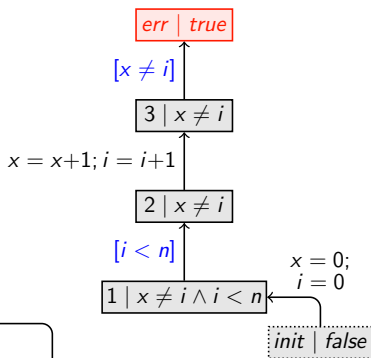
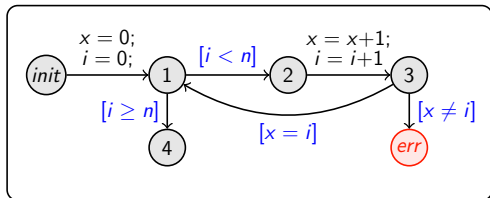
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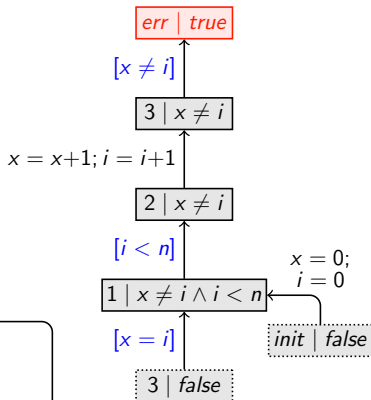
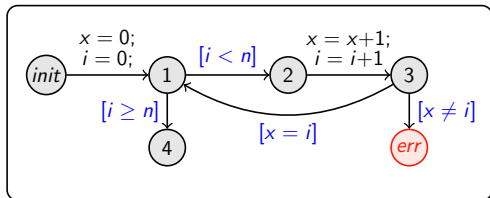
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## $k$ -induction for CFA

A CFA is correct if the following holds for some  $k > 0$ .

**1** **base case**

All paths of length at most  $k$  starting in *init* are safe.

**2** **induction step**

Each path of length  $k + 1$  that has a safe prefix of length  $k$  is also safe.

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verification algorithm

1  $k \leftarrow 1$

2 if base case does not hold then return **incorrect**

3 if induction step holds then return **correct**

4  $k \leftarrow k + 1$

5 goto 2

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- i.e. there is no feasible path from *init* to *err* of length at most  $k$

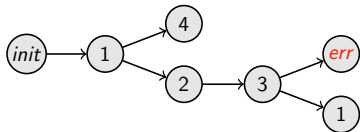
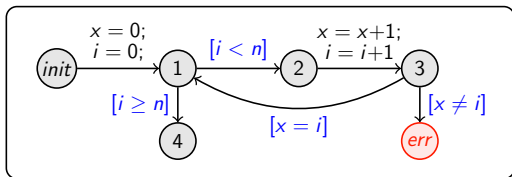


# relating $k$ -induction and BSE

## base case

All paths of length at most  $k$  starting in *init* are safe.

- i.e. there is no feasible path from *init* to *err* of length at most  $k$
- we can either search all relevant paths starting in *init*

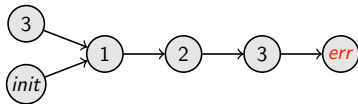
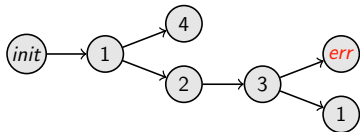
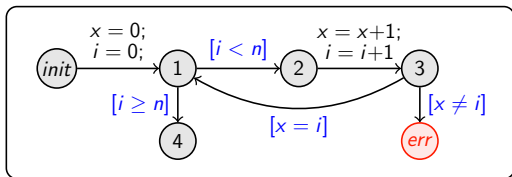


# relating $k$ -induction and BSE

## base case

All paths of length at most  $k$  starting in *init* are safe.

- i.e. there is no feasible path from *init* to *err* of length at most  $k$
- we can either search all relevant paths starting in *init*
- or search all relevant paths leading to *err*



### induction step

Each path of length  $k + 1$  that has a safe prefix of length  $k$  is also safe.

- i.e. there is no unsafe path of length  $k + 1$  with a safe prefix of length  $k$
- but a proper prefix of each unsafe path is safe
- i.e. there is no feasible path to *err* of length  $k + 1$
- i.e. the BSE tree is finite

### Theorem (BSE = $k$ -induction)

*If a CFA is incorrect, then the  $k$ -induction algorithm detects it and BSE tree will contain an unsafe path from init.*

*If a CFA is correct, then  $k$ -induction algorithm detects it if and only if the BFS tree is finite and contains no init node.*

Both approaches fail to detect correctness of a CFA that contains an unsafe path of length  $k$  for each  $k > 0$  (i.e. BSE tree is infinite).

- BSE (and k-induction) is incomplete

```
int n; // input
int x = 0;
int i = 0;
while (i < n) {
    ++x;
    ++i;
    assert(x == i);
}
```

- BSE (and k-induction) is incomplete

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int n; // input
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# BSE with Loop Folding (BSELF)

- BSE (and k-induction) is incomplete
- invariants in loops can help

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while (i < n) {
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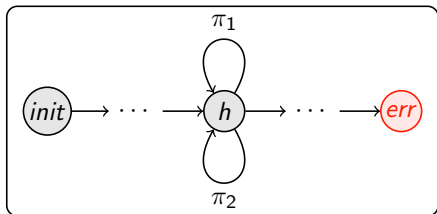
# BSE with Loop Folding (BSELF)

- BSE (and k-induction) is incomplete
- invariants in loops can help
- loop folding computes loop invariants from BSE states

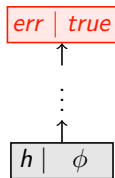
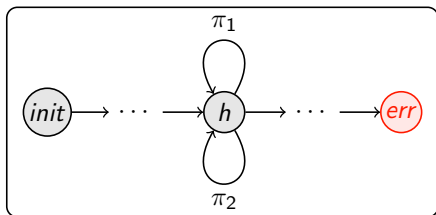
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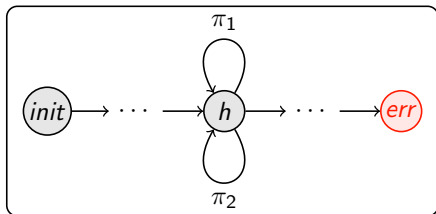
# BSE with Loop Folding (BSELF)



# BSE with Loop Folding (BSELF)



# BSE with Loop Folding (BSELF)



*err* | *true*

↑

$\vdots$

↑

*h* |  $\phi$



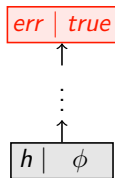
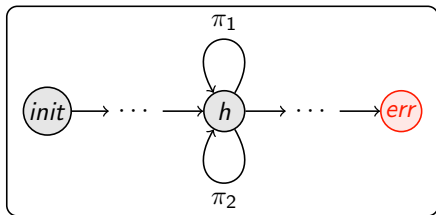
invariant for *h*

↓

*h* |  $\rho$

- when BSE reaches a node  $\boxed{h \mid \phi}$  where *h* is a loop header, we try to find an invariant  $\rho$  for *h* satisfying  $\rho \implies \neg\phi$
- if we succeed, we can drop this path

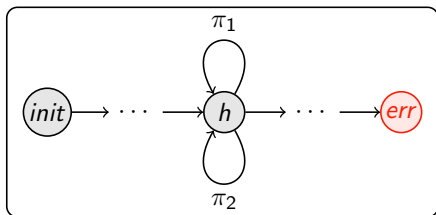
# BSE with Loop Folding (BSELF)



- we gradually create **invariant candidates**
- each candidate  $\xi$  satisfies  $\xi \implies \neg\phi$  and is **inductive**, i.e.

if  $h \mid \xi \rightarrow \dots \rightarrow h \mid \xi'$  then  $\xi' \implies \xi$

# BSE with Loop Folding (BSELF)



$err \mid true$

↑

⋮

$h \mid \phi$

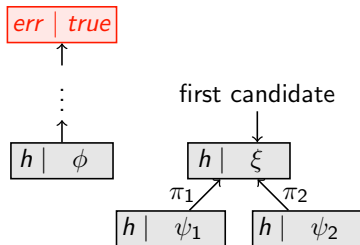
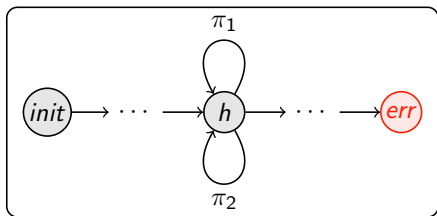
first candidate

↓

$h \mid \xi$

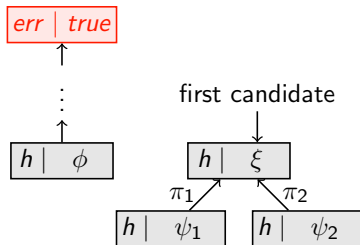
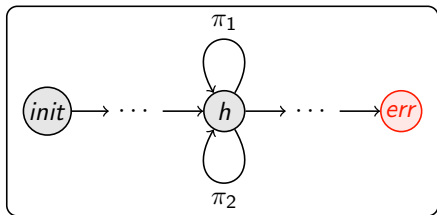
- we gradually create **invariant candidates**
- each candidate  $\xi$  satisfies  $\xi \implies \neg\phi$  and is **inductive**, i.e.  
if  $h \mid \xi \rightarrow \dots \rightarrow h \mid \xi'$  then  $\xi' \implies \xi$
- 1 find first invariant candidate  $\xi$  such that location  $h$  cannot be reached again from  $h \mid \xi$

# BSE with Loop Folding (BSELF)



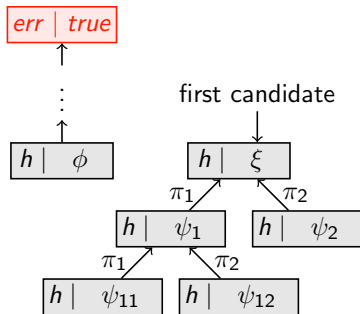
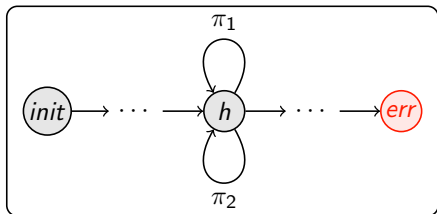
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- 2 if  $\xi$  is not an invariant, then compute  $\psi_1, \psi_2$

# BSE with Loop Folding (BSELF)



- we gradually create **invariant candidates**
- each candidate  $\xi$  satisfies  $\xi \implies \neg\phi$  and is **inductive**, i.e.  
if  $h \mid \xi \rightarrow \dots \rightarrow h \mid \xi'$  then  $\xi' \implies \xi$
- 1 find first invariant candidate  $\xi$  such that location  $h$  cannot be reached again from  $h \mid \xi$
- 2 if  $\xi$  is not an invariant, then compute  $\psi_1, \psi_2$
- 3 if  $\psi_i \implies \neg\phi$ , then  $\psi_i \vee \xi$  is also a candidate
- ⋮

# BSE with Loop Folding (BSELF)



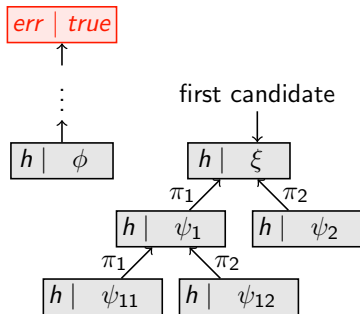
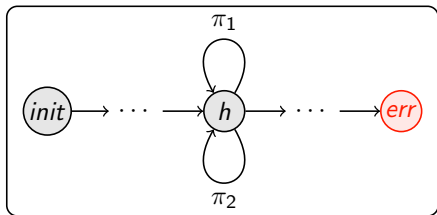
⋮

- candidates  $\psi_{11} \vee \psi_1 \vee \xi$  and  $\psi_{12} \vee \psi_1 \vee \xi$

⋮

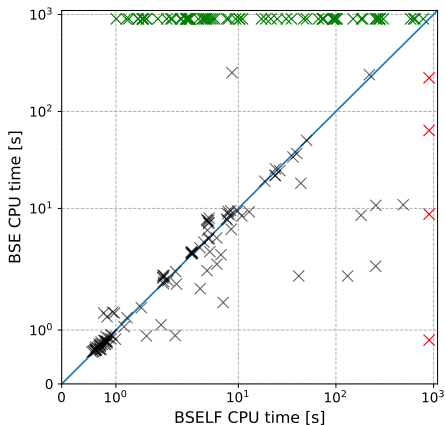


# BSE with Loop Folding (BSELF)



- we also apply overapproximation to candidates
- searching for an invariant is restricted to not get stuck
- if invariant is not found, we continue with BSE
- but candidates are saved and used for the construction of the first candidate when we enter  $h$  next time

BSE vs. BSELF on reachability safety tasks  
from the Loops subcategory of SV-COMP 2021  
(only benchmarks solved by BSE or BSELF)



## to win SV-COMP with symbolic execution

- first use static analyses and slicing to reduce the program
- tune symbolic executor to handle various code features precisely
- combine SE with BSE and potentially other techniques
- fix all bugs

# conclusion

## to win SV-COMP with symbolic execution

- first use static analyses and slicing to reduce the program
- tune symbolic executor to handle various code features precisely
- combine SE with BSE and potentially other techniques
- fix all bugs

Thank you.

